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Reverberant Shear Wave Elastography (R-SWE) Implementation and feasibility studies

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Elastography, what are the problems?

- Presence of reflected waves from organ boundaries and internal inhomogeneities
- Cause modal patterns in continuous wave applications backwards traveling waves in transient wave experiments.
- **Result** biased estimates of shear wave speed (SWS)

conventional methods assume shear wave propagation *parallel to the lateral direction*



Data from LogiqE9 system



Elastography, what are the problems?

- Presence of reflected waves from organ boundaries and internal inhomogeneities
- Solutions: Directional filters





Data from LogiqE9 system



Elastography, what are the limitations?

Penetration

- Liver -> Obesity, ascites
- Prostate -> 3-4cm. In large prostate, not deep enough to measure anterior zone
- Thyroid -> about 5.5cm. Large and deeply nodules cannot be properly assessed.

Shear wave propagation

 Breast -> Accuracy differs, problems with propagation of vibration energy. Weak in hard lesions

Pure gelatin based phantom: Good shear wave penetration and propagation

Gelatin + 6% castor oil: Problems with shear wave penetration and propagation



WFUMB guidelines and recommendations articles

Data from Samsung RS85 system



Motivation

- Reflections
- Multiple waves

Are they good or bad for shear wave measurements?

Penetration with good
How can we achieve it?



- Shear waves of random amplitude and phase propagates in all directions as a statistically isotropic distribution across 4π steradians (Parker et al., 2017. Ormachea et al., 2018.)
- Practically speaking, all tissue boundaries with reflections, and sources in the vicinity of the observation point contribute to the overall distribution.



Historical framework from *Acoustics* (A.D. Pierce, McGraw-Hill: New York, 1981, p. 257):





Schematic for the orientation of the imaging transducer and the object that has an isotropic random distribution of shear waves.

Parker et al. (2017)

• The monochromatic reverberant field pressure \widehat{P} at position ε and time t is:

$$\hat{P}(t,\boldsymbol{\varepsilon}) = \sum_{q} \hat{P}_{q} \exp\left[j\left(k\mathbf{n}_{q}\cdot\boldsymbol{\varepsilon}-\boldsymbol{\omega}_{0}\right)t\right]$$

where

 n_q : unit vectors in the direction of propagation of the q_{th} wave \hat{P}_q : independent, identically distributed variables of random magnitude and phase.





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Experiments

CIRS breast phantom



Elastic modulus 20 kPa

CIRS viscoelastic ph.



Elastic modulus 6 kPa

- A Verasonics ultrasound system & linear ultrasound transducer L7-4, center frequency was 5 MHz
- Phantom materials:
 - CIRS breast phantom
 - CIRS viscoelastic phantom
- Vibration frequencies:
 - [60 to 450] Hz, CIRS breast phantom
 - [60 to 220] Hz, CIRS viscoelastic ph.



Results: CIRS breast phantom – Single frequencies 450Hz



220Hz

360Hz





Results: CIRS breast phantom – Multi frequencies

300-360-400Hz 400-450-500Hz

140-180-220Hz





Results: CIRS viscoelastic phantom – Single frequencies

100Hz

140Hz

180Hz

220Hz





Results: CIRS viscoelastic phantom – Multi frequencies 60-100-140Hz 100-140Hz 140-180Hz 140-180Hz





Shear wave speed vs. Frequency CIRS Breast phantom CIRS viscoelastic phantom



Phantom	Experiment	Dispersion	Frequency range
CIRS breast	Single	0.28	180-300 Hz
	Multi	0.32	
CIRS viscoelastic	Single	0.59	100-220 Hz
	Multi freq.	0.56	

Comparison with another SWE modality





Results: CIRS breast phantom – Inclusion region



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Results: In vivo human liver



Patient were laid supine on a custom bed and the right arm abducted.

- A Verasonics ultrasound system & linear ultrasound transducer L7-4, center frequency was 5 MHz
- A volunteer patient for *in vivo* liver tissue.
- Vibration frequencies:
 - [40 to 240] Hz
- Scans under the requirements of informed consent and the University of Rochester Institutional Review Board



Results: In vivo human liver



Particle displacement signals



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Results: In vivo human liver





Preliminary results multi-frequencies: In vivo liver





Summary

 CIRS breast phantom -> lower dispersion than CIRS viscoelastic Expected since the viscoelastic phantom is a more dispersive media.

 No significant differences between single and multi-frequencies. Approach is feasible and can more quickly assess tissue properties.

 Unlike other modalities, R-SWE does not filter or select for SWs propagation directions

Facilitates the use for clinical applications.

Implementation is faster and simpler.



Summary

- The linear slope is comparable with results obtained with MRE (i.e. 0.75 m/s/100Hz at 25 Hz - 63 Hz (Klatt et al., 2007))
- An ideal reverberant field is obtained using multiple sources around the ROI.

However, the frequency ranges are different and cannot be strictly compared

However, reflections from boundaries and in homogeneities help to randomize the field in practice.

 Tissue boundaries and inhomogeneities produce more reflection waves Condition that is needed to create a reverberant field. Determination of shear wave sources is left for future research.



Summary

 Practical issue for clinicians concerns: time required for acquisition and processing of images High frame rate ultrasound scanning, high complexity shear wave algorithms are already implemented. Limiting factor integration vibration sources with the ultrasound system

• A future study will apply R-SWE at a deeper region in fatty patients.

Further study will involve the viscoelastic property estimation



Conclusion

- It was possible to estimate the viscoelastic properties in phantom materials and in vivo human tissue using the R-SWE approach.
- Consistent SWS estimation that enables characterization and differentiation of elastic and viscoelastic materials.
- Multifrequency approach shows that it is feasible and can more quickly assess the frequency dependence of SWS.



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